Figures

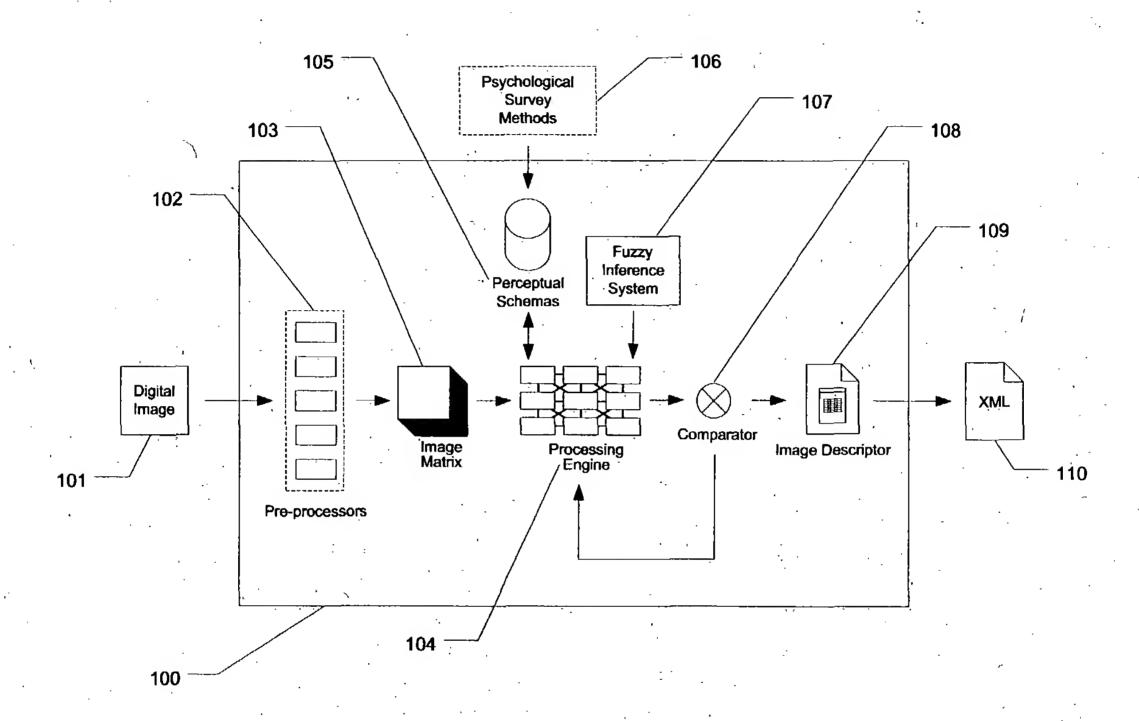


FIG. 1

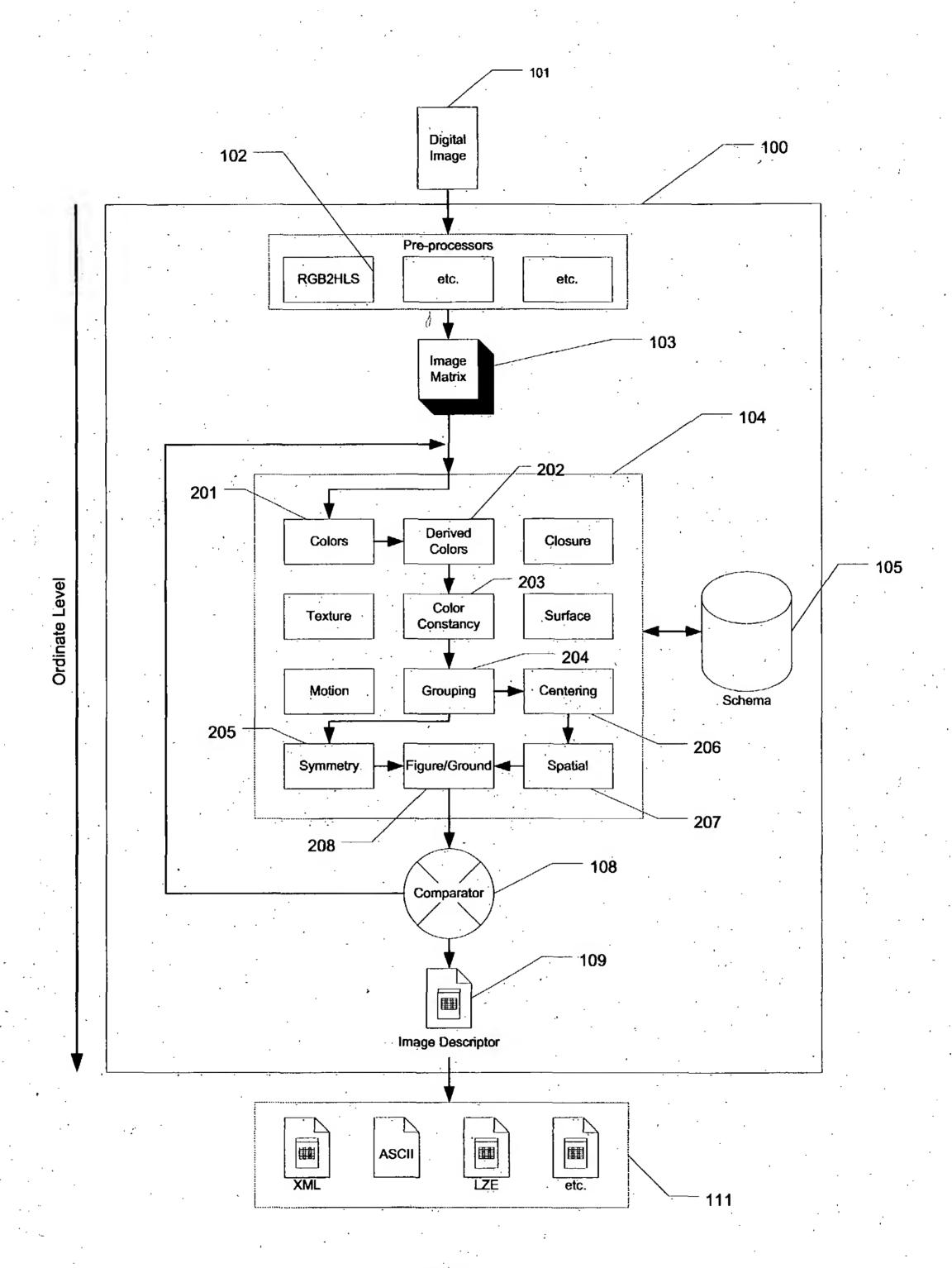


FIG. 2

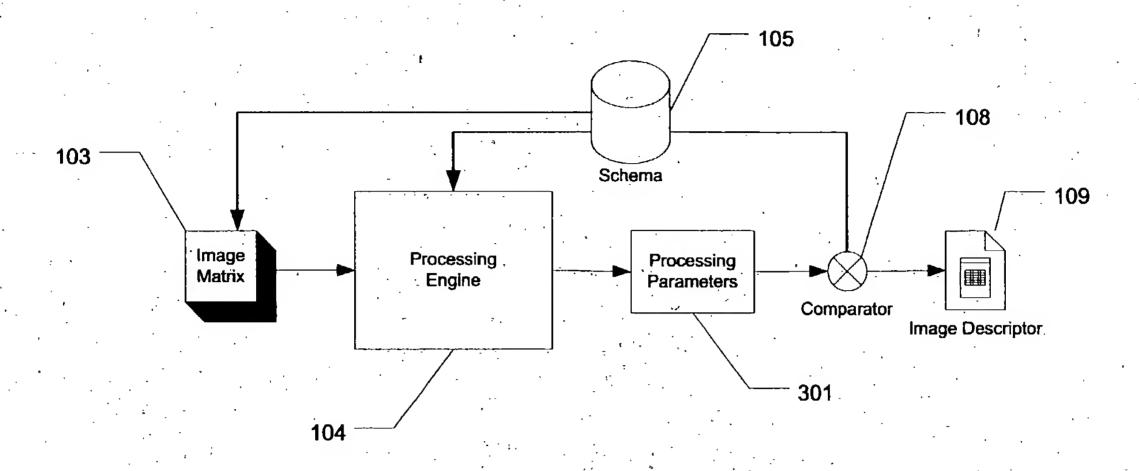


FIG. 3

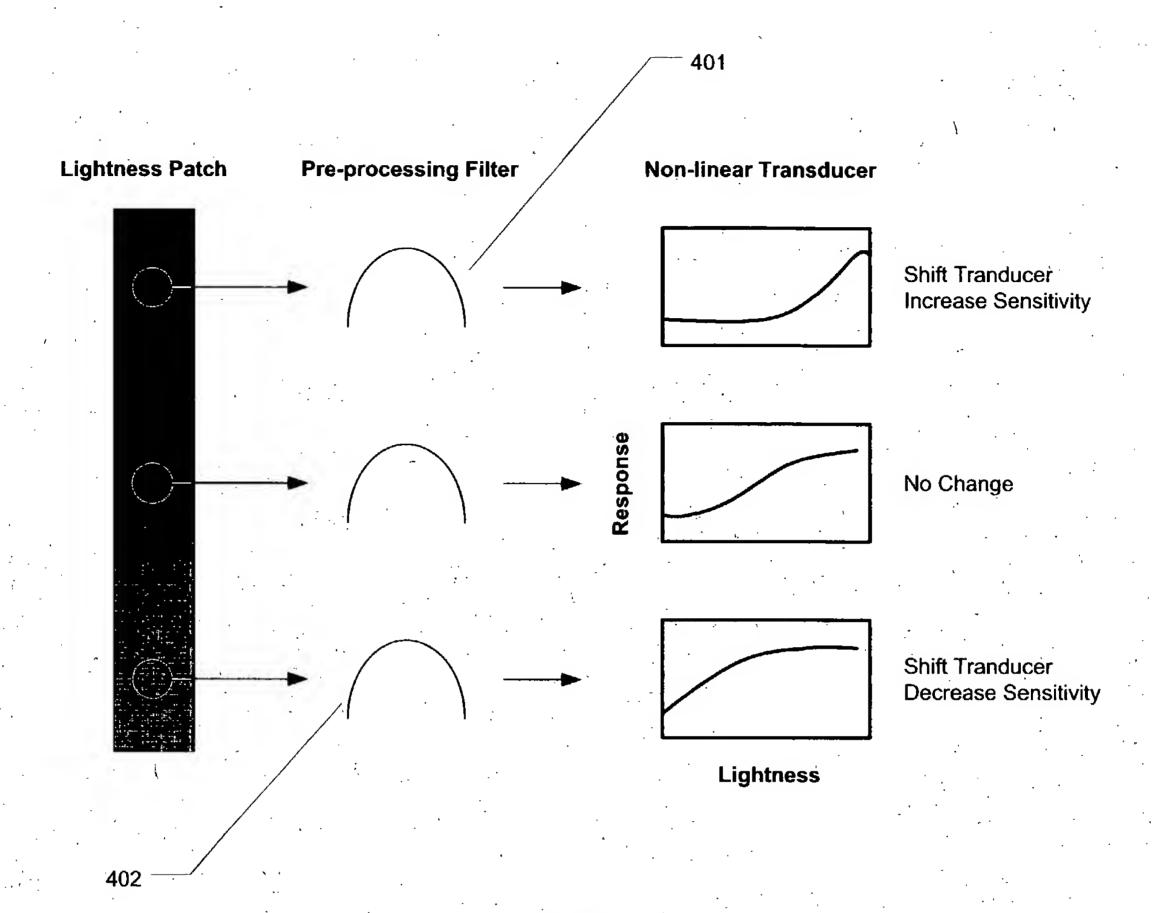


FIG. 4

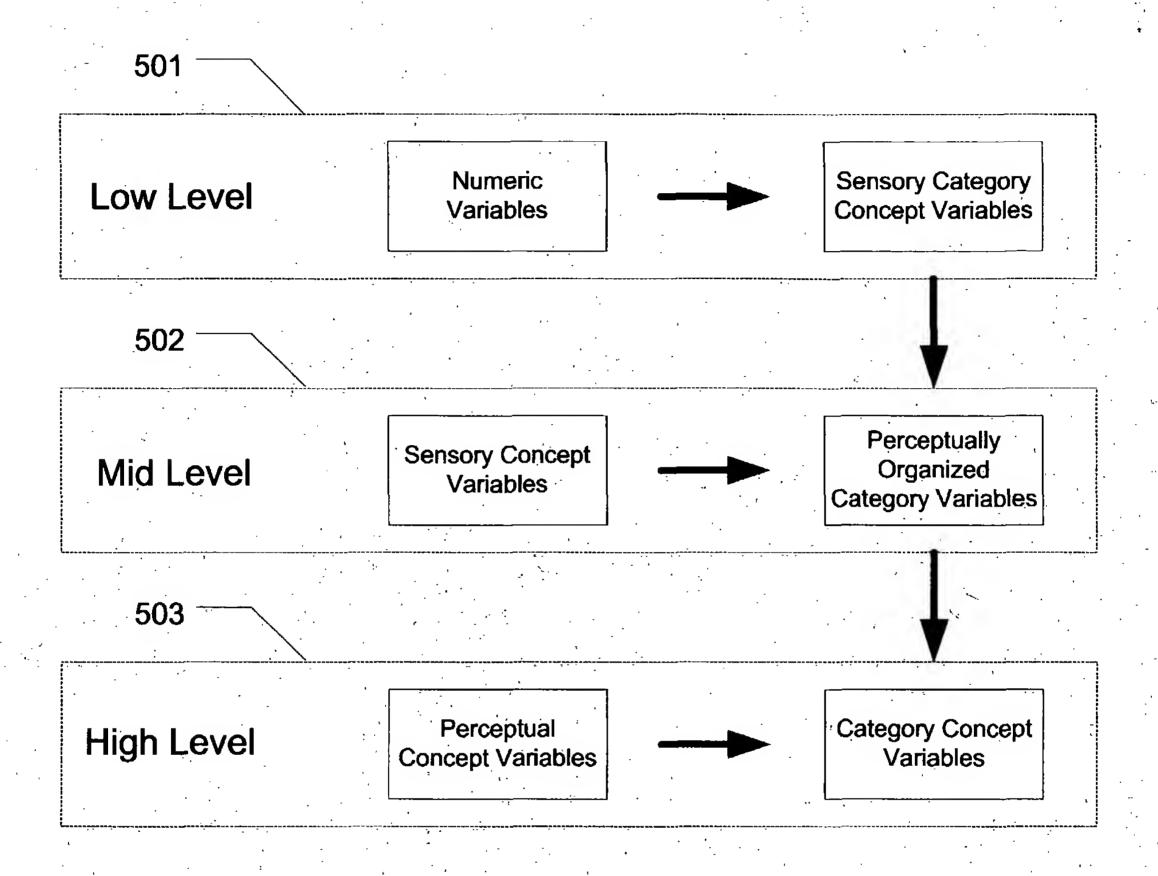


FIG. 5

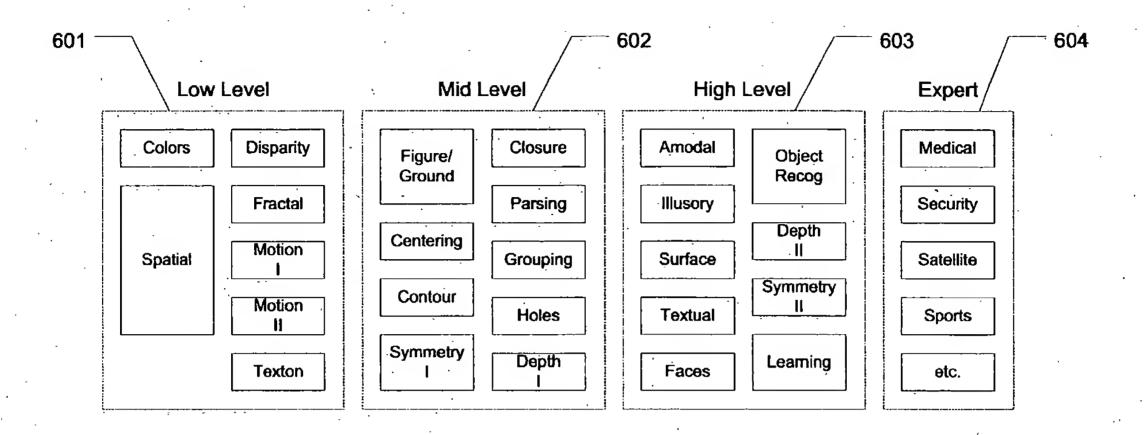


FIG. 6

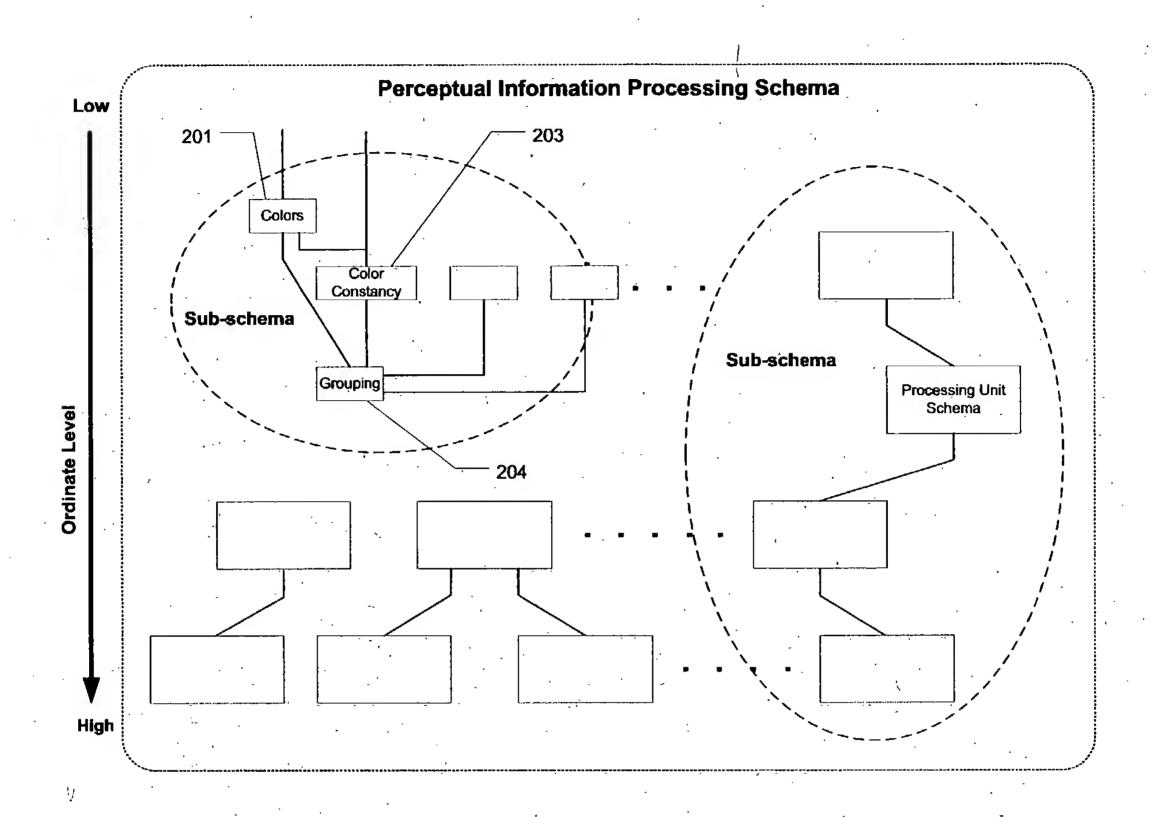


FIG. 7

FIG. 8

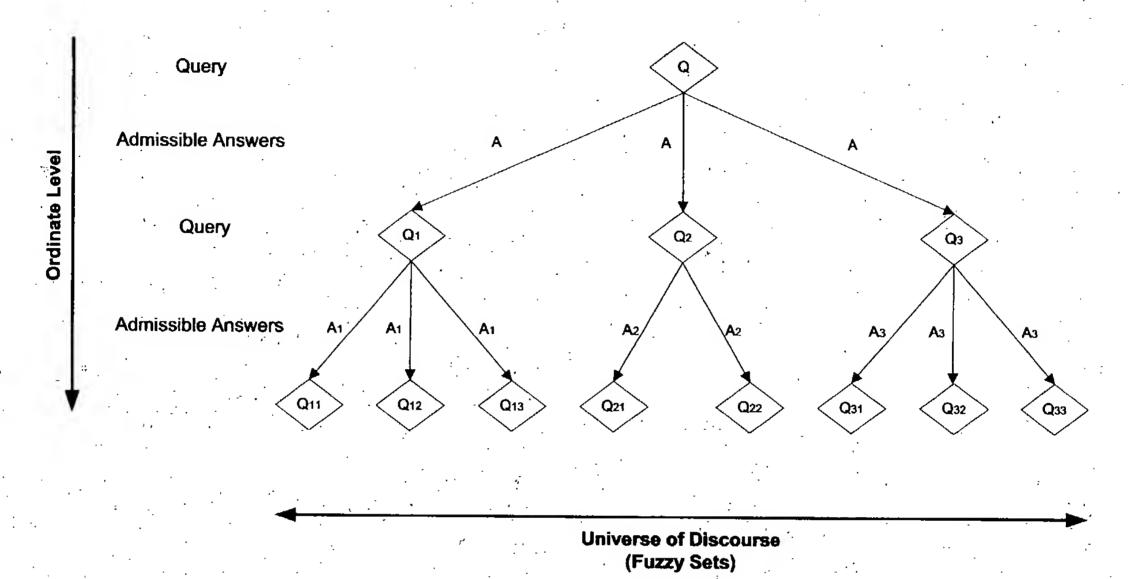
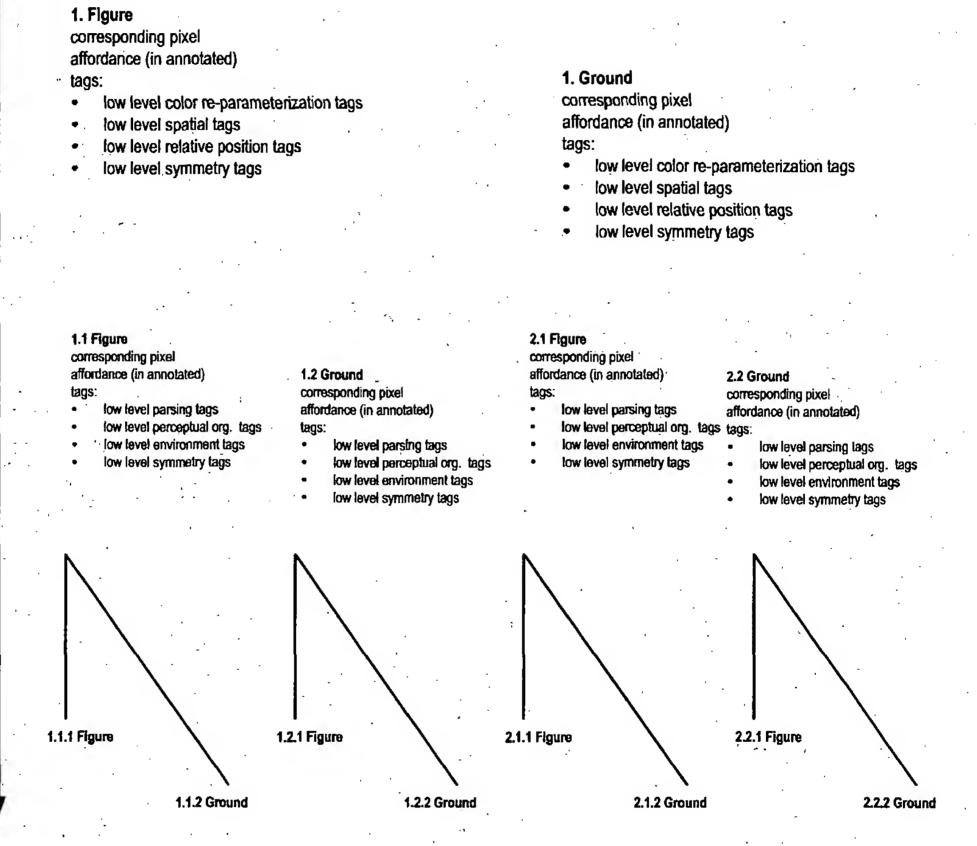


FIG. 9

Image Descriptor



PROCESSING DEPTH

ORDINATE LEVEL

FIG. 10

	А	В	С	D	. E	F F	G	Н	1	J	ĸ
·1	•	Command Note	≖intért(filo namé)	end(figure(irrege),level) Level: 0 = all		=ponent(image(cat) number)	=group(cell,align(orientation,se ries)) Series: 1 = series 1	rgroup(cell_align(orientation, se rcs)) Series: 2 = series 2		=CatDist(cat)/Count(cat)	=CalDist(call)/Count(call)
2		Example	~insert(*CCTV638_1630,LZ*)	-end(figure(C7),0)	rcenter(tagPbetLocation(end(ti gure(E7))))	-porient(image (E7),5)	=group(E7,#figm(F7,1))	-group(E7, elign(F7,2))		-CalDist(17)/Count(17)	-CarlDist(J7)/Count(J7)
3	friden	Time					Lane 1	Lane 2	Thmu	Obstance Lane 1	Distance Lane 2
: 4	1	9:10			• • • • • • •		***************************************		 9-10)	
. 5		9:20		2	\$ \$ \$			8	9.20	,	. 0.3
. 6	3	9:30			* * *				9.30	11.5	

FIG. 11

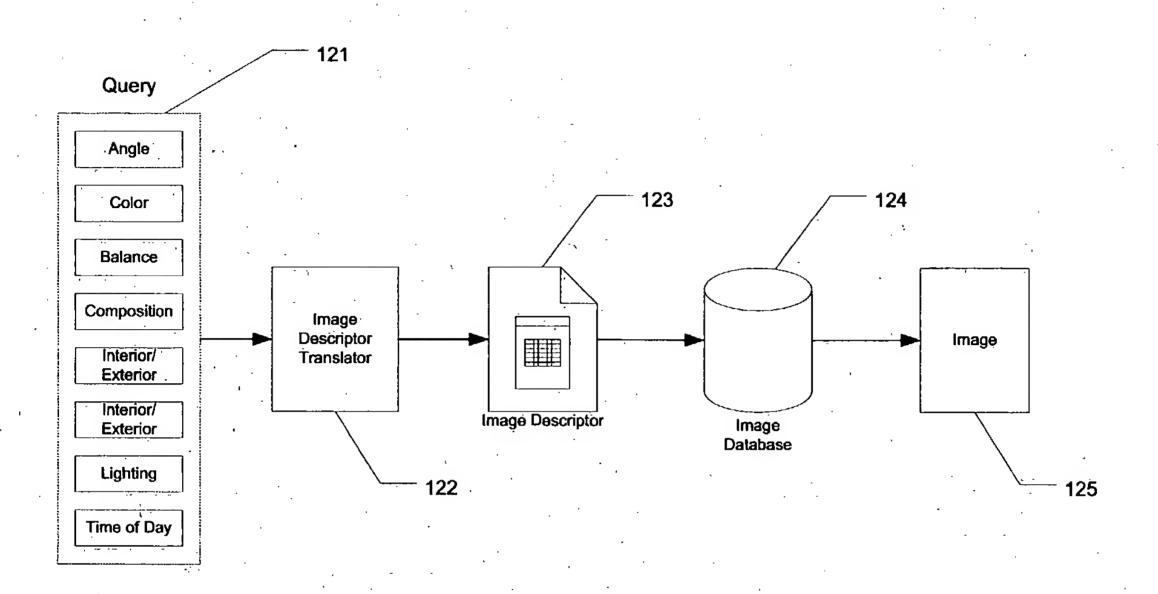


FIG. 12

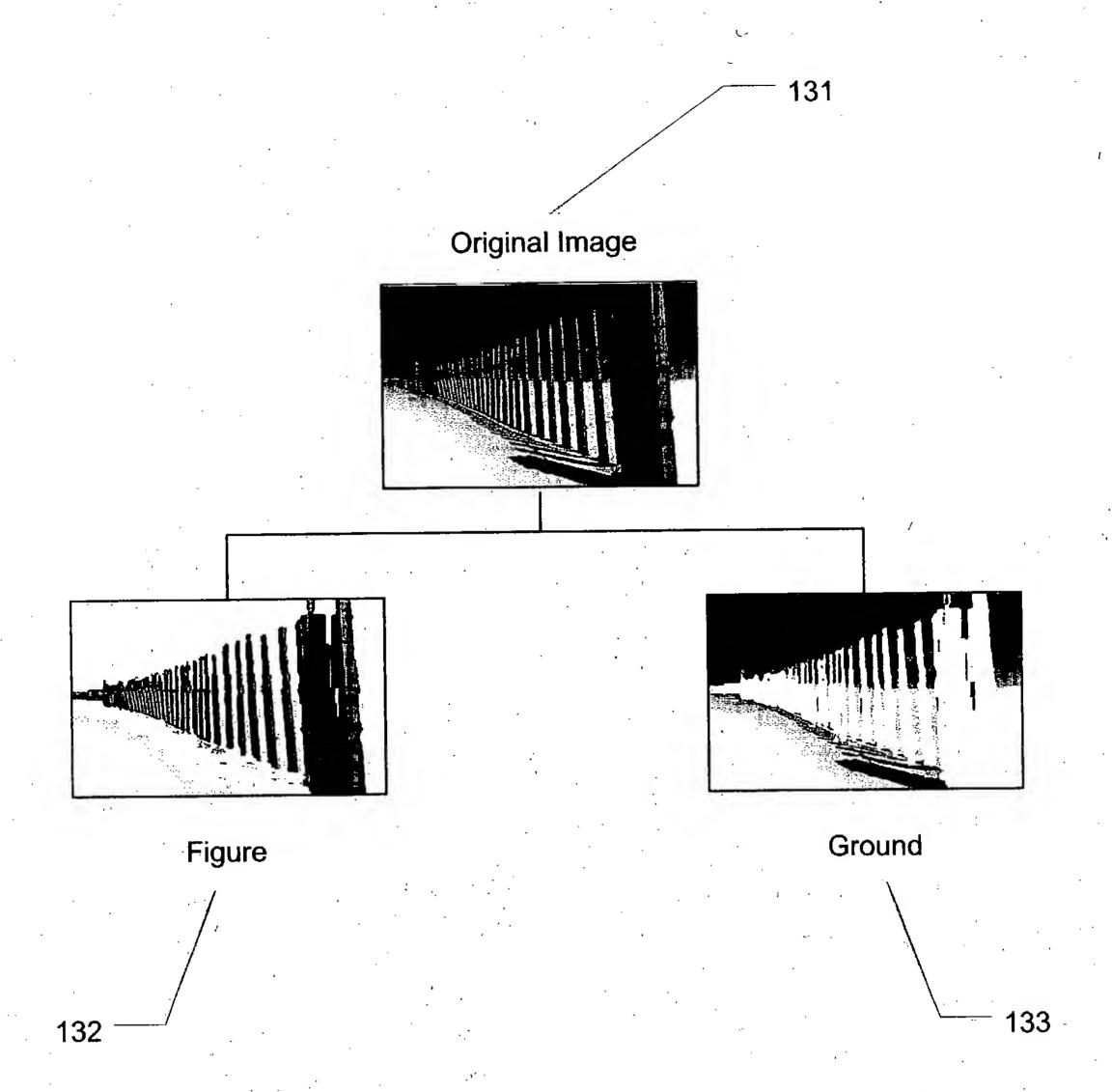


FIG. 13